# GRADIENT ESTIMATES FOR SOME DIFFUSION SEMIGROUPS 

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#### Abstract

Consider the semigroup $P_{t}$ of an elliptic diffusion; we describe a simple stochastic method providing gradient estimates on $P_{t} f$. If $N$ is a manifold endowed with a connection, the method can also be applied to the associated nonlinear semigroup $Q_{t}$ acting on $N$-valued maps. With a localization technique, we deduce gradient estimates for real harmonic functions or $N$-valued harmonic maps. Moreover, the results are extended to a class of hypoelliptic diffusions.


Keywords. Gradient estimates, Harmonic functions, Harmonic maps, Elliptic diffusions, Hypoelliptic diffusions.

Mathematics Subject Classification (2000). 60J60 60H07 58E20 58J65

## 1 Introduction

Consider the semigroup $P_{t}=e^{t L}$ of a diffusion with generator $L$ on a manifold $M$. If $f$ is a real-valued function defined on $M$, the derivative $d\left(P_{t} f\right)$ of the function $x \mapsto P_{t} f(x)$ takes its values in the cotangent bundle $T^{\star} M$, and we are interested in estimations of this derivative with stochastic methods. More precisely, we look for estimates of the form

$$
\begin{equation*}
\left|d\left(P_{t} f\right)\right| \leq C_{q, t} P_{t}\left(|f|^{q}\right)^{1 / q} \tag{1.1}
\end{equation*}
$$

for $t>0$ and $q>1$. This problem can be generalised in several ways. First, it can be localized; the function $h(t, x)=P_{t} f(x)$ is solution of the heat equation

$$
\begin{equation*}
\frac{\partial}{\partial t} h=L h, \quad h(0, .)=f \tag{1.2}
\end{equation*}
$$

on $\mathbb{R}_{+} \times M$, and if $D$ is an open subset of $M$, one can consider a function $h$ which is only solution on $\mathbb{R}_{+} \times D$, and estimate its derivative $d h(t, x)$ with respect to $x$. For instance, by considering functions $h(x)$ which do not depend on $t$, we want to obtain estimates for the derivative of functions which are harmonic on $D$. Notice that such functions have a well known stochastic interpretation; they map the diffusion to a real martingale. A second generalisation is to replace the target space $\mathbb{R}$ of the function by a manifold $N$ endowed with a connection; the connection provides the exponential map $\exp _{y}: T_{y} N \rightarrow N$ and its reverse map $\exp _{y}^{-1}$ which is defined on a neighbourhood of $y$; if $f: M \rightarrow N$ is a $C^{2}$ map, one can consider the tension field of $f$, namely

$$
L_{N} f: M \rightarrow T N \quad x \mapsto L_{N} f(x)=L\left(\exp _{f(x)}^{-1} f\right)(x) \in T_{f(x)} N .
$$

Then the semigroup $P_{t}$ is replaced by a nonlinear semigroup $Q_{t}$ which acts on functions $f: M \rightarrow N$ and is given by the equation

$$
\begin{equation*}
\frac{d}{d t} Q_{t} f=L_{N}\left(Q_{t} f\right), \quad Q_{0} f=f \tag{1.3}
\end{equation*}
$$

This semigroup has a stochastic interpretation similar to the real-valued case, but real martingales have to be replaced by $N$-valued martingales (we refer to [14] for basic results about manifold-valued martingales). One can prove that $Q_{t} f$ is defined for any $t \geq 0$ if $N$ satisfies some convexity assumptions, for instance if $N$ is a regular geodesic ball of a Riemannian manifold (see the definition in Example 3.2); the stochastic method for the construction of $Q_{t} f$ is to prove the existence of $N$-valued martingales with prescribed
terminal values, see $[17,22,23,1]$. The derivative $d\left(Q_{t} f\right)$ takes its values in the bundle of linear maps $L(T M, T N)=\bigcup_{(x, y)} L\left(T_{x} M, T_{y} N\right)$, and we would like to obtain an estimate similar to the real-valued case (1.1).

First notice that if $L$ satisfies Hrmander's conditions, then it is well known that its semigroup has a smooth density and can be written as

$$
\begin{equation*}
P_{t} f(x)=\int_{M} f(z) p(t, x, z) d z \tag{1.4}
\end{equation*}
$$

Then estimates on the derivative of $p(t, x, z)$ with respect to $x$ such as [20] imply that $P_{t} f$ is smooth, and moreover, one can deduce estimates on $d\left(P_{t} f\right)$. However, this method cannot be applied for $d\left(Q_{t} f\right)$ because the nonlinear semigroup has no representation of type (1.4); a calculation using local coordinates enables to study the smoothness of $Q_{t} f$ (see [24], see also [16] for symmetric diffusions with an analytical method), but this technique does not provide good gradient estimates.

Thus we are looking for a direct method which does not use the density of the diffusion. A first possibility is to use a coupling method; this method has been worked out in the elliptic case for $P_{t} f$ in [7]; it has also been extended in [19] to the study of the $N$-valued semigroup $Q_{t} f$, but it is not simple (one needs to study the Hlder continuity before the Lipschitz continuity), and it does not cover the case where $N$ is a general regular geodesic ball. Another possibility is to apply the Bismut formula of [6] which gives an expression for $d\left(P_{t} f\right)$ involving $f$ but not its derivatives; this type of formula has been widely studied and enables to obtain some estimates in the elliptic case, see $[12,26,27,29,28]$. Some formulae can also be given for the manifoldvalued case, see [4, 2], but gradient estimates for general regular geodesic balls are again not given. The method has also been extended in [3] to the hypoelliptic case, but it does not seem easy to deduce gradient estimates for the manifold-valued case.

Here, we consider a method which relates these gradient estimates to the estimation of the quadratic variation of a martingale (real or on $N$ ); then, by applying Burkholder and Doob inequalities, one notices that this quadratic variation is dominated by the final value of the martingale (or of some function of the martingale in the manifold case, see [8] for the Burkholder inequalities in this case). This method is worked out in the elliptic case, in Section 2 for the real-valued case, and in Section 3 for the manifold-valued case; in particular it provides estimates of $d\left(Q_{t} f\right)$ when $N$ is a regular Riemannian geodesic ball, or when $N$ is a small enough subset of a manifold endowed with a connection. Moreover, we show in Section 4 that the method also
works for a class of hypoelliptic diffusions; more precisely, if $L$ is written in Hrmander's form

$$
\begin{equation*}
L=\Xi_{0}+\sum_{i=1}^{n} \Xi_{i}^{2} / 2, \tag{1.5}
\end{equation*}
$$

we obtain the estimate when the tangent space at a point $x$ is linearly generated by $\Xi_{i}$ and the commutators $\left[\Xi_{i}, \Xi_{j}\right]$ taken at $x$; the simplest example is the hypoelliptic Brownian motion on the Heisenberg group; this result is obtained by using the invariance by rotation of the Wiener process. The more general hypoelliptic case (where one considers Lie brackets of arbitrary length) apparently cannot be dealt with by our method, so the problem of obtaining gradient estimates for $Q_{t} f$ in this framework is still open.

## 2 The elliptic case

The results of this section are not new and can be deduced from Malliavin's calculus or Bismut's formula as it was described in the introduction; however the method of this section will again be applied subsequently (for the manifold-valued and hypoelliptic cases), and we prefer to introduce it in a simple framework. We suppose that $M$ is a finite dimensional $C^{\infty}$ manifold and that $X_{t}$ is a diffusion on $M$ with generator $L$ written in Hrmander's form (1.5) with $C^{\infty}$ vector fields $\Xi_{i}$. If $W_{t}^{i}, 1 \leq i \leq n$, are standard independent real Wiener processes, this diffusion can be written as the solution $X_{t}=X_{t}^{x}$ of the Stratonovich equation

$$
\begin{equation*}
\delta X_{t}=\Xi_{0}\left(X_{t}\right) \delta t+\sum_{i=1}^{n} \Xi_{i}\left(X_{t}\right) \delta W_{t}^{i}, \quad X_{0}=x \tag{2.1}
\end{equation*}
$$

One can choose a $C^{\infty}$ modification of the stochastic flow $x \mapsto X_{t}^{x}$. The superscript $x$ will often be omitted.

### 2.1 Gradient estimates on the semigroup

Suppose that the diffusion is elliptic, so that the vector space generated by $\Xi_{i}(x), 1 \leq i \leq n$, is the whole tangent space $T_{x} M$, and let us estimate $d\left(P_{t} f\right)$ for a bounded Borel function $f$ and a time $t>0$. The function $d\left(P_{t} f\right)$ takes its values in the cotangent bundle $T^{\star} M$, and we need a Riemannian metric on $M$ in order to estimate it; this provides a norm on $T_{x} M \sim T_{x}^{\star} M$; however, the order of the estimate will not depend on this metric if $M$ is compact.

Theorem 1. Assume that $M$ is compact and that the diffusion is elliptic. Let $q>1$. Then there exists a constant $C$ such that

$$
\begin{equation*}
\left|d\left(P_{t} f\right)(x)\right| \leq \frac{C}{\sqrt{t} \wedge 1} P_{t}\left(|f|^{q}\right)(x)^{1 / q} \tag{2.2}
\end{equation*}
$$

for any $x$ in $M$, any $t>0$ and any bounded Borel function $f$.
Remark 2.1. In all this work, the letter $C$ will denote a positive constant which may change from a formula to the other.

Proof. It is sufficient to prove the result for smooth functions $f$ because the general case can be dealt with by approximating $f$ by $P_{\varepsilon} f$ as $\varepsilon \downarrow 0$. The proof can also be reduced to the time interval $0 \leq t \leq 1$; then, for $t>1$, one can write $P_{t} f=P_{1} P_{t-1} f$, and therefore

$$
\left|d\left(P_{t} f\right)\right| \leq C P_{1}\left(\left|P_{t-1} f\right|^{q}\right)^{1 / q} \leq C P_{t}\left(|f|^{q}\right)^{1 / q} .
$$

So let $t \leq 1$. The process

$$
Y_{s}^{x}=P_{t-s} f\left(X_{s}^{x}\right), \quad 0 \leq s \leq t
$$

is a martingale which is given by

$$
\begin{equation*}
Y_{s}=P_{t} f(x)+\sum_{i} \int_{0}^{s} \Xi_{i}\left(P_{t-u} f\right)\left(X_{u}\right) d W_{u}^{i} \tag{2.3}
\end{equation*}
$$

By differentiating $Y_{s}^{x}$ with respect to $x$, if $J_{s}: T_{x} M \rightarrow T_{X_{s}^{x}} M$ is the Jacobian of the map $x \mapsto X_{s}^{x}$, we obtain a process

$$
Y_{s}^{\prime}=d\left(P_{t-s} f\right)\left(X_{s}\right) J_{s},
$$

with values in $T_{x}^{\star} M$. We deduce from the compactness of $M$ that $\mathbb{E}\left|Y_{s}^{\prime}\right|^{2}$ is bounded with respect to $x$; in particular, we can exchange the conditional expectation and the differentiation in order to prove that $Y_{s}^{\prime}$ inherits the martingale property of $Y_{s}$. Thus

$$
\begin{equation*}
Y_{0}^{\prime}=\frac{1}{t} \mathbb{E} \int_{0}^{t} Y_{s}^{\prime} d s, \tag{2.4}
\end{equation*}
$$

so

$$
\begin{align*}
\left|d\left(P_{t} f\right)(x)\right| & =\frac{1}{t}\left|\mathbb{E} \int_{0}^{t} d\left(P_{t-s} f\right)\left(X_{s}\right) J_{s} d s\right| \\
& \leq \frac{1}{\sqrt{t}}\left\|\sup _{s \leq 1}\left|J_{s}\right|\right\|_{q^{\prime}}\left\|\left(\int_{0}^{t}\left|d\left(P_{t-s} f\right)\left(X_{s}\right)\right|^{2} d s\right)^{1 / 2}\right\|_{q} \tag{2.5}
\end{align*}
$$

with $1 / q+1 / q^{\prime}=1$, and where $\left|J_{s}\right|$ is the operator norm of $J_{s}$. The process $J_{t}$ is obtained by differentiating the equation (2.1) of $X_{t}$, and since $M$ is compact, standard estimates show that the $L^{q^{\prime}}$ norm is bounded (independently of $x$ ). Moreover, it follows from (2.3) and the ellipticity assumption that the integral in the right hand side of (2.5) is dominated by the quadratic variation

$$
\begin{equation*}
\langle Y, Y\rangle_{t}=\int_{0}^{t} \sum_{i}\left|\Xi_{i}\left(P_{t-s} f\right)\left(X_{s}\right)\right|^{2} d s \tag{2.6}
\end{equation*}
$$

of the martingale $Y_{s}$, so

$$
\left|d\left(P_{t} f\right)(x)\right| \leq \frac{C}{\sqrt{t}}\left\|\langle Y, Y\rangle_{t}^{1 / 2}\right\|_{q}
$$

Finally, we deduce from the Burkholder and Doob inequalities that

$$
\left|d\left(P_{t} f\right)(x)\right| \leq \frac{C}{\sqrt{t}}\left\|Y_{t}\right\|_{q}=\frac{C}{\sqrt{t}} P_{t}\left(|f|^{q}\right)(x)^{1 / q} .
$$

Remark 2.2. In (2.4), one can replace $Y_{s}^{\prime}$, and therefore $J_{s}$, by its conditional expectation $\bar{J}_{s}$ given $\left(X_{u} ; u \leq s\right)$, so that

$$
\begin{equation*}
d\left(P_{t} f\right)(x)=\frac{1}{t} \mathbb{E} \int_{0}^{t} d\left(P_{t-s} f\right)\left(X_{s}\right) \bar{J}_{s} d s \tag{2.7}
\end{equation*}
$$

In particular, let $M$ be a compact Riemannian manifold and suppose that $L=\Delta / 2$ for the Laplace-Beltrami operator $\Delta$; then $X_{t}$ is the Brownian motion on $M$. One can consider $M$ as a Riemannian submanifold of an Euclidean space $\mathbb{R}^{n}$ with canonical basis $\left(e_{i} ; 1 \leq i \leq n\right)$; then $X_{t}$ can be viewed as the solution of an equation (2.1) where $\Xi_{0}(x)=0$ and $\Xi_{i}(x)$, $1 \leq i \leq n$, are the orthogonal projections of the vectors $e_{i}$ on $T_{x} M$; with this representation, the process $X_{t}$ becomes a gradient Brownian system, see [10] for details; it is uniformly elliptic. In this case, $\bar{J}_{s}$ is computed in $[13,11]$ (this is called filtering out redundant noise). It appears that it is the solution of the covariant differential equation

$$
\frac{D}{d s} \bar{J}_{s}=-\frac{1}{2} \operatorname{Ric}^{\star}\left(X_{s}\right) \bar{J}_{s}
$$

for the Ricci curvature considered as a linear operator on the tangent space; thus a lower bound on the Ricci curvature implies an upper bound on $\left|\bar{J}_{s}\right|$ and can be used in (2.7); then one can go on as in the previous proof. The
advantage of this approach is that it provides bounds with geometrical meaning; in functional analytic terms, it is related to the Bochner formula (see [25]). For more general diffusions, these bounds can also be obtained by applying the iterated "carr du champ" $\left(\Gamma_{2}\right)$ technique, and an analogue of the Ricci curvature is again involved, see [5] or Lemma 1.3 of [21]. However, the method of Theorem 1 can be found simpler if the diffusion is given as a solution of a stochastic differential equation.
Remark 2.3. Another advantage of $\bar{J}_{s}$ with respect to $J_{s}$ is that $\bar{J}_{s}$ is in $L^{\infty}$. Thus (2.5) can be written with $q=1$. However, the Doob inequality is not valid for $q=1$, so we cannot obtain (2.2); we only can use a modification of Doob's inequality (see (25.2) in [9]) to get

$$
\left|d\left(P_{t} f\right)(x)\right| \leq \frac{C}{\sqrt{t} \wedge 1}\left(1+P_{t}\left(|f| \log ^{+}|f|\right)(x)\right)
$$

Remark 2.4. One can add a constant to the function $f$ in Theorem 1 , so for any real $y_{0}$ one has

$$
\begin{equation*}
\left|d\left(P_{t} f\right)(x)\right| \leq \frac{C}{\sqrt{t} \wedge 1} P_{t}\left(\left|f-y_{0}\right|^{q}\right)(x)^{1 / q} . \tag{2.8}
\end{equation*}
$$

In particular, for $q=2$ and $y_{0}=P_{t} f(x)$, we obtain the standard deviation of $f\left(X_{t}^{x}\right)$ in the right-hand side.
Remark 2.5. One can also estimate higher order derivatives of $P_{t} f$. For the second order derivative, one studies the martingale $Y_{s}^{\prime \prime}$ which is the second order derivative of $Y_{s}^{x}$. The value $Y_{0}^{\prime \prime}$ is given by an equation similar to (2.4), and the right hand side is estimated by means of the quadratic variations of $Y_{s}$ and $Y_{s}^{\prime}$.

### 2.2 Localization and estimates for harmonic functions

The above procedure can be localized in order to estimate derivatives of functions $h(t, x)$ which are solutions of the heat equation (1.2) on a part of $\mathbb{R}_{+} \times M$; the localization can also be used to study $P_{t} f$ when $M$ is not compact (see also subsection 2.3 below). If $D$ is an open subset of $M$, we consider the space-time process $Z_{s}^{t, x}=\left(t-s, X_{s}^{x}\right), 0 \leq s \leq t$, and we let $\tau$ be the first exit time of $\mathbb{R}_{+} \times D$ for this process. Then a smooth function $h(t, x)$ is solution of the heat equation $\partial h / \partial t=L h$ on $\mathbb{R}_{+} \times D$ if $h\left(Z_{s \wedge \tau}^{t, x}\right)$ is a martingale for any $(t, x)$. Like previously, we fix a Riemannian metric on $M$.

Theorem 2. Suppose that the diffusion is elliptic and consider a smooth bounded function $h$ which is solution of the heat equation on $\mathbb{R}_{+} \times D$. Let $\rho$ be the distance function to the complement of $D$, and let $q>1$. Let dh $(t, x)$ be the derivative of $h(t, x)$ with respect to $x$. For any compact subset $K$ of $M$, there exists a $C_{K}>0$ which does not depend on $h$ such that

$$
\begin{equation*}
|d h(t, x)| \leq \frac{C_{K}}{1 \wedge \sqrt{t} \wedge \rho(x)}\left(\mathbb{E}\left|h\left(Z_{\tau}^{t, x}\right)\right|^{q}\right)^{1 / q} \tag{2.9}
\end{equation*}
$$

for $x \in K \cap D$ and $t>0$. In particular, if $h(t, x)=h(x)$ is harmonic on $D$, then

$$
|d h(x)| \leq \frac{C_{K}}{\rho(x) \wedge 1}\left(\mathbb{E}\left|h\left(X_{\tau}^{x}\right)\right|^{q}\right)^{1 / q}
$$

where $h\left(X_{\tau}^{x}\right)$ is defined as the limit of $h\left(X_{t}^{x}\right)$ on $\{\tau=\infty\}$.
Reduction to the compact case. We first verify that the proof of Theorem 2 can be reduced to the case of a compact manifold $M$. We have to prove that any point $x_{0}$ of $M$ has a neighbourhood, for instance a ball $B_{0}$, on which the estimate (2.9) holds. Let $B_{1}$ be a ball which is slightly larger than $B_{0}$, let $\tau_{1}$ be the exit time of $\mathbb{R}_{+} \times\left(D \cap B_{1}\right)$, and let $\rho_{1}$ is the distance function to the complement of $D \cap B_{1}$. We have

$$
\mathbb{E}\left|h\left(Z_{\tau}^{t, x}\right)\right|^{q} \geq \mathbb{E}\left|h\left(Z_{\tau_{1}}^{t, x}\right)\right|^{q} \quad \text { and } \quad \rho(x) \wedge 1 \leq C \rho_{1}(x)
$$

for $x \in B_{0}$, where the first inequality holds because $Y_{s}=h\left(Z_{s}^{t, x}\right)$ is a martingale up to time $\tau$. We deduce that it is sufficient to prove the estimate (2.9) for $D \cap B_{1}$ instead of $D$. The ball $B_{1}$ can be embedded isometrically in a compact manifold, so we can suppose that $M$ is compact and take $K=M$.

Proof of Theorem 2 in the compact case. Like previously, it is sufficient to consider the case $t \leq 1$. Consider on $\mathbb{R}_{+} \times M$ the distance function

$$
\delta_{\star}\left((t, x),\left(t^{\prime}, x^{\prime}\right)\right)=\max \left(\frac{\delta_{M}\left(x, x^{\prime}\right)}{\alpha}, \sqrt{\left|t^{\prime}-t\right|}\right)
$$

for the Riemannian distance $\delta_{M}$ on $M$, and where $\alpha>1$ is a constant which will be chosen later. We also consider the function $\rho_{\star}(t, x)$ which is the distance to the complement of $\mathbb{R}_{+} \times D$, so that

$$
\rho_{\star}(t, x)=\frac{\rho(x)}{\alpha} \wedge \sqrt{t} .
$$

Fix $(t, x)$. For $0<r<\rho_{\star}^{2}(t, x) \leq 1$, let

$$
\begin{aligned}
\tau(r) & =\inf \left\{s \geq 0 ; \delta_{\star}\left((t, x), Z_{s}\right) \geq \sqrt{r}\right\} \\
& =\inf \left\{s \geq 0 ; \delta_{M}\left(x, X_{s}\right) \geq \alpha \sqrt{r}\right\} \wedge r
\end{aligned}
$$

By differentiating the martingale property of $Y_{s}=h\left(Z_{s}\right)$, we verify that $Y_{s}^{\prime}=d h\left(Z_{s}\right) J_{s}$ is a local martingale up to time $\tau$, where $J_{s}$ is the Jacobian of $X_{s}^{x}$ as in the proof of Theorem 1 (there is a small difficulty due to the time $\tau$, but the result can be proved with a time change on the diffusion outside a compact subset of $D$, so that it does not quit $D$; this implies that $Y_{s}^{\prime}$ is a local martingale up to the exit time of the arbitrary compact subset). The condition on $r$ implies that $\tau(r)<\tau$, so

$$
\begin{aligned}
\left|Y_{0}^{\prime}\right| \leq & \frac{1}{r}\left\|\int_{0}^{r}\left|Y_{s \wedge \tau(r)}^{\prime}\right| d s\right\|_{1} \\
\leq & \frac{1}{r}\left\|\int_{0}^{\tau(r)}\left|Y_{s}^{\prime}\right| d s\right\|_{1}+\frac{1}{r}\left\|(r-\tau(r))\left|Y_{\tau(r)}^{\prime}\right|\right\|_{1} \\
\leq & \frac{1}{\sqrt{r}}\left\|\left(\int_{0}^{\tau(r)}\left|d h\left(Z_{s}\right)\right|^{2} d s\right)^{1 / 2}\right\|\left\|_{q}\right\|_{0 \leq s \leq r}\left|J_{s}\right| \|_{q^{\prime}} \\
& +\mathbb{P}[\tau(r)<r]^{1 / q^{\prime}}\left\|Y_{\tau(r)}^{\prime}\right\|_{q}
\end{aligned}
$$

if $1 / q+1 / q^{\prime}=1$. The moments of $\sup _{s}\left|J_{s}\right|$ are finite, and the first $L^{q}$ norm is estimated as in Theorem 1 by means of the quadratic variation of $Y_{s}=h\left(Z_{s}\right)$, and therefore by $\left\|Y_{\tau(r)}\right\|_{q} \leq\left\|Y_{\tau}\right\|_{q}$. In the second term, standard estimates show that the probability of

$$
\{\tau(r)<r\}=\left\{\sup _{s<r} \delta_{M}\left(x, X_{s}\right) \geq \alpha \sqrt{r}\right\}
$$

can be made arbitrarily small if $\alpha$ is chosen large enough. Thus we choose $\alpha$ so that

$$
\begin{equation*}
\left|Y_{0}^{\prime}\right| \leq \frac{C}{\sqrt{r}}\left\|Y_{\tau}\right\|_{q}+\frac{1}{4}\left\|Y_{\tau(r)}^{\prime}\right\|_{q} \tag{2.10}
\end{equation*}
$$

On the other hand

$$
\rho_{\star}\left(Z_{\tau(r)}\right) \geq \rho_{\star}\left(Z_{0}\right)-\sqrt{r},
$$

so

$$
\begin{aligned}
& \rho_{\star}\left(Z_{0}\right)\left|Y_{0}^{\prime}\right| \leq \frac{C}{\sqrt{r}} \rho_{\star}\left(Z_{0}\right)\left\|Y_{\tau}\right\|_{q} \\
& \quad+\frac{1}{4} \frac{\rho_{\star}\left(Z_{0}\right)}{\rho_{\star}\left(Z_{0}\right)-\sqrt{r}}\left\|\rho_{\star}\left(Z_{\tau(r)}\right) Y_{\tau(r)}^{\prime}\right\|_{q} .
\end{aligned}
$$

If we choose $r=\rho_{\star}^{2}\left(Z_{0}\right) / 4$, then we obtain

$$
\rho_{\star}\left(Z_{0}\right)\left|Y_{0}^{\prime}\right| \leq C\left\|Y_{\tau}\right\|_{q}+\frac{1}{2}\left\|\rho_{\star}\left(Z_{\tau(r)}\right) Y_{\tau(r)}^{\prime}\right\|_{q} .
$$

More generally, if now $\tau^{\prime}$ is any optional time such that $\tau^{\prime}<\tau$, the same method enables to estimate $\rho_{\star}\left(Z_{\tau^{\prime}}\right)\left|Y_{\tau^{\prime}}^{\prime}\right|$, and by taking the $L^{q}$ norm, we show that there exists an optional time $\tau^{\prime}<\tau^{\prime \prime}<\tau$ such that

$$
\left\|\rho_{\star}\left(Z_{\tau^{\prime}}\right) Y_{\tau^{\prime}}^{\prime}\right\|_{q} \leq C\left\|Y_{\tau}\right\|_{q}+\frac{1}{2}\left\|\rho_{\star}\left(Z_{\tau^{\prime \prime}}\right) Y_{\tau^{\prime \prime}}^{\prime}\right\|_{q} .
$$

By taking the supremum over all optional times which are less than $\tau$, we obtain

$$
\sup _{\tau^{\prime}}\left\|\rho_{\star}\left(Z_{\tau^{\prime}}\right) Y_{\tau^{\prime}}^{\prime}\right\|_{q} \leq 2 C\left\|Y_{\tau}\right\|_{q}
$$

We deduce (2.9) by taking $\tau^{\prime}=0$.

### 2.3 Uniform estimates in the non compact case

If $M$ is not compact, we now wonder whether Theorem 1 holds, or whether Theorem 2 holds for a constant $C_{K}=C$ which does not depend on $K$. We first have to choose on $M$ a Riemannian metric so that the diffusion is uniformly elliptic, that is

$$
\sum_{i}\left|\Xi_{i} f(x)\right|^{2} \geq c|d f(x)|^{2}
$$

for any smooth function $f$. Then, in order to work out the estimates of Theorem 1, we first have to justify the exchange of the conditional expectation and differentiation in (2.4); then we need the uniform boundedness of the moments of $\sup _{s \leq 1}\left|J_{s}\right|$; to this end, we have to choose a convenient representation (1.5) of the generator. For Theorem 2, we also have to verify that the probability of $\{\tau(r)<r\}$ is uniformly small (for $r \leq 1$ ) if $\alpha$ is chosen large enough.
Example 2.1. If $M=\mathbb{R}^{d}$, one can write the equation (2.1) as an It equation

$$
d X_{t}=b\left(X_{t}\right) d t+\sum_{i} \xi_{i}\left(X_{t}\right) d W_{t}^{i}, \quad X_{0}=x
$$

If the matrix $\xi \xi^{\star}$ is bounded and uniformly elliptic and if moreover $b$ and the Jacobian matrices of $b$ and $\xi_{i}$ are bounded, then one can verify with the above procedure that Theorems 1 and 2 hold uniformly.

Example 2.2. Let $M$ be a closed submanifold of an Euclidean space; suppose that $M$ is endowed with its induced Riemannian metric and $L=\Delta / 2$; then the diffusion is uniformly elliptic. If we apply the method of Remark 2.2 , then $\bar{J}_{s}$ is conveniently estimated as soon as the Ricci curvature of $M$ is bounded below; however, obtaining an intrinsic condition ensuring the justification of (2.4) is not so easy, see chapters 6 and 10 of [25]. On the other hand, the estimation of the exit time of small balls (more precisely of $\mathbb{P}[\tau(r)<r]$ ) can also be worked out when the Ricci curvature is bounded below with the technique of [15], and we obtain (2.9) uniformly.
Example 2.3. Suppose that there exists a group $G$ which acts transitively on $M$, and that the diffusion is invariant under this action; this means that $\left(X_{t}^{g . x}\right)$ and ( $g \cdot X_{t}^{x}$ ) have the same law; an example is the Brownian motion on an homogeneous space. Then it is clear that the estimation of $d h(t, x)$ for solutions $h$ of (1.2) can be reduced to the estimation at a fixed $x=x_{0}$, so Theorem 2 holds uniformly, and Theorem 1 also holds.

## 3 Estimation for harmonic maps

Let us now consider the nonlinear semigroup $Q_{t}$ defined for $N$-valued maps by (1.3) for a given connection on the manifold $N$. We suppose that $Q_{t} f$ is well defined, and that $(t, x) \mapsto Q_{t} f(x)$ is smooth for $t>0$; in the elliptic case, this holds under some convexity conditions on $N$, see [19, 2, 24] for probabilistic proofs. We want to estimate $d\left(Q_{t} f\right)$ and prove an analogue of (2.8). The stochastic interpretation of $Q_{t}$ is similar to $P_{t}$; the connection enables to consider a notion of $N$-valued continuous martingale, and the process $Y_{s}^{x}=Q_{t-s} f\left(X_{s}^{x}\right)$ is for any $x$ a $N$-valued martingale, so $Q_{t} f(x)$ is the initial value of the martingale with final value $f\left(X_{t}^{x}\right)$ (this martingale is unique under the convexity assumptions). The aim of this section is to prove the following result (see also the extension to the nonlinear heat equation at the end of the section).

Theorem 3. Suppose that $M$ is compact, that the diffusion is elliptic, and that $N$ is a relatively compact open subset of a manifold $\widetilde{N}$ endowed with an extension of the connection of $N$. We suppose that $\widetilde{N}$ satisfies the following convexity conditions; there exists a $p \geq 1$, a Riemannian distance $\delta$ on $\tilde{N}$ and nonnegative functions $\phi$ and $\psi$ on $\widetilde{N} \times \widetilde{N}$ such that

$$
\phi\left(y_{0}, y\right)=0 \Longleftrightarrow \psi\left(y_{0}, y\right)=0 \Longleftrightarrow y_{0}=y
$$

and

1. The function $\phi$ is convex and $\phi\left(y_{0}, y\right) \sim \delta^{p}\left(y_{0}, y\right)$ as $y \rightarrow y_{0}$.
2. For any $y_{0}$, the function $y \mapsto \psi\left(y_{0}, y\right)$ is $C^{2}$ and strictly convex (its Hessian is positive definite).

Then, for any $q>p$, there exists a $C$ such that

$$
\begin{equation*}
\left|d\left(Q_{t} f\right)(x)\right| \leq \frac{C}{\sqrt{t} \wedge 1} \mathbb{E}\left[\delta^{q}\left(y_{0}, f\left(X_{t}\right)\right)\right]^{1 / q} \tag{3.1}
\end{equation*}
$$

for any $y_{0}$ in $N$, any $x$ in $M$, any $t>0$ and any function $f: M \rightarrow N$ such that the solution $Q_{t} f$ of (1.3) is well defined, $N$-valued, and smooth for $t>0$.

Remark 3.1. The manifold $\widetilde{N} \times \widetilde{N}$ is endowed with the product connection; saying that $\phi$ is convex means that it is convex along the geodesic curves; if $U_{t}^{1}$ and $U_{t}^{2}$ are $N$-valued martingales, this implies that $\phi\left(U_{t}^{1}, U_{t}^{2}\right)$ is a submartingale. Notice also that the result (3.1) is stated for the distance $\delta$, but it also holds for other Riemannian distances on $\widetilde{N}$, since all these distances are equivalent on $N$.

The convexity conditions of the theorem look stronger than the " $p$-convexity" conditions used in $[23,1]$. However, one can give basically the same examples of manifolds $N$ satisfying them.
Example 3.1. On any manifold endowed with a connection and for any $p>1$, any point has neighbourhoods $N \subset \widetilde{N}$ satisfying the above conditions. The function constructed in Proposition 2.5 of [2] can be proved to be a convenient function $\phi$ for some distance $\delta$, and one can take $\psi=\delta^{2}$.
Example 3.2. One can choose for $N \subset \widetilde{N}$ regular geodesic balls in a Riemannian manifold with distance $\delta_{0}$; this means that the sectional curvatures of the manifold are bounded above by some $\kappa \geq 0$, and that $N \subset \widetilde{N}$ are balls (for the distance $\delta_{0}$ ) with empty cut loci and with radii less than $\pi /(2 \kappa)$ (there is no condition on the radii if $\kappa=0$ ). In this situation, the existence of $\phi$ has been obtained in [18] by generalizing the case of the sphere (notice that $\delta$ is generally different from $\delta_{0}$ ); moreover, this function $\phi$ is strictly convex outside the diagonal (one can also use the method of [23] to construct $\phi$, but one needs some extra work in order to obtain the strict convexity); the value of $p$ depends on the radius of $\widetilde{N}$. On the other hand, there exists a $c>0$ such that $y \mapsto \delta^{2}\left(y_{0}, y\right)$ is strictly convex for $\phi\left(y_{0}, y\right) \leq c$; then the function

$$
\psi=\delta^{2}+\beta\left((\phi-c / 2)^{+}\right)^{3}
$$

satisfies the convexity condition of Theorem 3 if $\beta$ is chosen large enough.

Example 3.3. If $\widetilde{N}$ is a Cartan-Hadamard manifold with distance $\delta_{0}$ (a simply connected Riemannian manifold with nonpositive sectional curvatures), then any ball $N \subset \widetilde{N}$ satisfies the conditions with $p=1, \phi=\delta=\delta_{0}$ and $\psi=\delta^{2}$. Moreover, the constants involved in the proof below do not depend on the size of the ball, so the estimate holds for the whole (non compact) manifold and the result of Theorem 3 becomes quite similar to the result (2.8) for the real-valued case.

Proof of Theorem 3. As in Theorem 1, we suppose that $Q_{t} f$ is smooth for $t \geq 0$ (otherwise approximate $f$ by $Q_{\varepsilon} f$ ) and we let $t \leq 1$. Let us consider the $N$-valued martingale $Y_{s}^{x}=Q_{t-s} f\left(X_{s}^{x}\right)$ and its derivative $Y_{s}^{\prime}=d\left(Q_{t-s} f\right)\left(X_{s}\right)$ with respect to $x$; this is a process with values in the bundle $L(T M, T N)$. Let $\left|Y_{s}^{\prime}\right|$ be its operator norm (associated to the Riemannian metrics $\delta_{M}$ and $\delta$ on $M$ and $N)$. For any $x$ and $x^{\prime}$, the convexity of $\phi$ implies that $\phi\left(Y_{s}^{x}, Y_{s}^{x^{\prime}}\right)$ is a submartingale, so by dividing by $\delta_{M}\left(x, x^{\prime}\right)$ and taking the limit as $x^{\prime} \rightarrow x$, we deduce that $\left|Y_{s}^{\prime}\right|^{p}$ is a submartingale. Thus

$$
\left|Y_{0}^{\prime}\right|^{p} \leq \frac{1}{t} \mathbb{E} \int_{0}^{t}\left|Y_{s}^{\prime}\right|^{p} d s
$$

Case $p \leq 2$. In this case,

$$
\begin{aligned}
\left|Y_{0}^{\prime}\right| & \leq \frac{1}{\sqrt{t}}\left\|\left(\int_{0}^{t}\left|Y_{s}^{\prime}\right|^{2} d s\right)^{1 / 2}\right\|_{p} \\
& \leq \frac{1}{\sqrt{t}}\left\|\sup _{s \leq 1}\left|J_{s}\right|\right\|_{q^{\prime}}\left\|\left(\int_{0}^{t}\left|d\left(Q_{t-s} f\right)\left(X_{s}\right)\right|^{2} d s\right)^{1 / 2}\right\|_{q}
\end{aligned}
$$

for $q>p$ and $1 / q+1 / q^{\prime}=1 / p$. The last term can again be dominated by means of the quadratic variation $\langle\langle Y\rangle\rangle$ of $Y_{s}$ (computed for instance for the distance $\delta$ ) so that

$$
\left|Y_{0}^{\prime}\right| \leq \frac{C}{\sqrt{t}}\left\|\langle\langle Y\rangle\rangle_{t}^{1 / 2}\right\|_{q} .
$$

On the other hand, the derivatives of $\psi$ are dominated by $\psi^{1 / 2}$, and $\psi$ is strictly convex, so we can apply the Burkholder inequalities of [8] for manifold-valued martingales to obtain

$$
\left|Y_{0}^{\prime}\right| \leq \frac{C}{\sqrt{t}}\left\|\sup _{s \leq t} \psi\left(Y_{0}, Y_{s}\right)^{1 / 2}\right\|_{q} .
$$

Since $\psi \asymp \delta^{2} \asymp \phi^{2 / p}$, we get

$$
\left|Y_{0}^{\prime}\right| \leq \frac{C}{\sqrt{t}}\left\|\sup _{s \leq t} \phi\left(Y_{0}, Y_{s}\right)\right\|_{q / p}^{1 / p} .
$$

Finally we can apply the Doob inequality to the submartingale $\phi\left(Y_{0}, Y_{s}\right)$ and obtain

$$
\left|Y_{0}^{\prime}\right| \leq \frac{C}{\sqrt{t}}\left\|\phi\left(Y_{0}, Y_{t}\right)\right\|_{q / p}^{1 / p} \leq \frac{C^{\prime}}{\sqrt{t}}\left\|\delta\left(Y_{0}, Y_{t}\right)\right\|_{q} .
$$

Moreover

$$
\begin{align*}
\left\|\delta\left(Y_{0}, Y_{t}\right)\right\|_{q} & \leq \delta\left(y_{0}, Y_{0}\right)+\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q} \\
& \leq C\left|\phi\left(y_{0}, Y_{0}\right)\right|^{1 / p}+\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q}  \tag{3.2}\\
& \leq C\left\|\phi\left(y_{0}, Y_{t}\right)\right\|_{q / p}^{1 / p}+\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q} \leq C^{\prime}\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q}
\end{align*}
$$

so the proof of the theorem is complete in the case $p \leq 2$.
Case $p>2$. In this case, we have

$$
\begin{aligned}
\left|Y_{0}^{\prime}\right|^{p} & \leq \frac{1}{r} \mathbb{E} \int_{0}^{r}\left|Y_{s}^{\prime}\right|^{p} d s \\
& \leq \frac{1}{r} \mathbb{E}\left[\sup _{s \leq r}\left|Y_{s}^{\prime}\right|^{p-2} \int_{0}^{r}\left|Y_{s}^{\prime}\right|^{2} d s\right] \\
& \leq \frac{1}{r} \mathbb{E}\left[\sup _{s \leq r}\left|Y_{s}^{\prime}\right|^{p}\right]^{1-2 / p} \mathbb{E}\left[\left(\int_{0}^{r}\left|Y_{s}^{\prime}\right|^{2} d s\right)^{p / 2}\right]^{2 / p} \\
& \leq \frac{C}{r} \mathbb{E}\left[\sup _{s \leq r}\left|Y_{s}^{\prime}\right|^{p}\right]^{1-2 / p} \mathbb{E}\left[\langle\langle Y\rangle\rangle_{r}^{q / 2}\right]^{2 / q}
\end{aligned}
$$

By applying the Doob inequality to the first term, and the Burkholder and Doob inequalities to the second term (as in the case $p \leq 2$ ), we obtain

$$
\left|Y_{0}^{\prime}\right|^{p} \leq \frac{C}{r} \mathbb{E}\left[\left|Y_{r}^{\prime}\right|^{q}\right]^{(p-2) / q} \mathbb{E}\left[\delta\left(Y_{0}, Y_{r}\right)^{q}\right]^{2 / q}
$$

On the other hand, for any $c>0$, there exists a $C>0$ such that

$$
x y \leq c x^{p /(p-2)}+C y^{p / 2} .
$$

for positive $x$ and $y$. By applying this property for $c=1 / 4$, we get

$$
\begin{align*}
\left|Y_{0}^{\prime}\right| & \leq \frac{C}{r^{1 / p}}\left\|Y_{r}^{\prime}\right\|_{q}^{(p-2) / p}\left\|\delta\left(Y_{0}, Y_{r}\right)\right\|_{q}^{2 / p} \\
& \leq \frac{1}{4}\left\|Y_{r}^{\prime}\right\|_{q}+\frac{C^{\prime}}{\sqrt{r}}\left\|\delta\left(Y_{0}, Y_{r}\right)\right\|_{q} . \tag{3.3}
\end{align*}
$$

We have obtained an estimate for $Y_{0}^{\prime}$; for $u<u+r \leq t$, we deduce similarly an estimate for $Y_{u}^{\prime}$, and by taking the $L^{q}$ norm, we obtain

$$
\left\|Y_{u}^{\prime}\right\|_{q} \leq \frac{1}{4}\left\|Y_{u+r}^{\prime}\right\|_{q}+\frac{C}{\sqrt{r}}\left\|\delta\left(Y_{u}, Y_{u+r}\right)\right\|_{q}
$$

Moreover, a technique similar to (3.2), based on the convexity of $\phi$ enables to prove that

$$
\left\|\delta\left(Y_{u}, Y_{u+r}\right)\right\|_{q} \leq C\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q}
$$

so

$$
\left\|Y_{u}^{\prime}\right\|_{q} \leq \frac{1}{4}\left\|Y_{u+r}^{\prime}\right\|_{q}+\frac{C}{\sqrt{r}}\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q} .
$$

By choosing $r=\frac{3}{4}(t-u)$, we deduce that for any $0 \leq u<t$, there exists $u<s<t$ given by $s=u+r=u+\frac{3}{4}(t-u)$ such that

$$
\sqrt{t-u}\left\|Y_{u}^{\prime}\right\|_{q} \leq \frac{1}{2} \sqrt{t-s}\left\|Y_{s}^{\prime}\right\|_{q}+C\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q}
$$

If we take the supremum with respect to $u$, we obtain

$$
\sup _{0 \leq u<t}\left(\sqrt{t-u}\left\|Y_{u}^{\prime}\right\|_{q}\right) \leq 2 C\left\|\delta\left(y_{0}, Y_{t}\right)\right\|_{q}
$$

and deduce the estimate (3.1) for $d\left(Q_{t} f\right)(x)=Y_{0}^{\prime}$.
If now $h(t, x)$ is solution of the nonlinear heat equation $\partial h / \partial t=L_{N} h$ on $\mathbb{R}_{+} \times D$, one can apply jointly the technique of Theorem 3 and the localization procedure of Theorem 2. If for instance $p>2$, one considers $Y_{s}=h\left(Z_{s}\right)$, $Y_{s}^{\prime}=d h\left(Z_{s}\right) J_{s}$, and $\left|Y_{s}^{\prime}\right|^{p}$ is a submartingale up to time $\tau$; by stopping the processes at $\tau(r)$ one obtains

$$
\left|Y_{0}^{\prime}\right|^{p} \leq \frac{1}{r} \mathbb{E} \int_{0}^{\tau(r)}\left|Y_{s}^{\prime}\right|^{p} d s+\frac{1}{r} \mathbb{E}\left[(r-\tau(r))\left|Y_{\tau(r)}^{\prime}\right|^{p}\right]
$$

The first term can be estimated as in (3.3), and since the probability of $\{\tau(r)<r\}$ can be made small, the second term can be estimated by the second term of (2.10). Thus we obtain

$$
\left|Y_{0}^{\prime}\right| \leq \frac{1}{4}\left\|Y_{\tau(r)}^{\prime}\right\|_{q}+\frac{1}{4}\left\|Y_{\tau(r)}^{\prime}\right\|_{q}+\frac{C}{\sqrt{r}}\left\|\delta\left(y_{0}, Y_{\tau(r)}\right)\right\|_{q}
$$

Then we multiply by $\rho_{\star}\left(Z_{0}\right)$, and the study can be completed as in Section 2. The result is

$$
|d h(t, x)| \leq \frac{C_{K}}{1 \wedge \sqrt{t} \wedge \rho(x)} \mathbb{E}\left[\delta^{q}\left(y_{0}, h\left(Z_{\tau}^{t, x}\right)\right)\right]^{1 / q}
$$

## 4 The hypoelliptic case

Let us now consider the non elliptic case; as it has been explained in the introduction (see also Remark 4.2 below), we cannot deal with the general case, but have to restrict to the case where the tangent space is generated by the $C^{\infty}$ vector fields $\Xi_{i}$ and their commutators; a particular (non compact) case is the classical Brownian motion on the Heisenberg group; it is a three-dimensional process consisting of a two-dimensional standard Brownian motion and of its Lvy area. Like previously, the following result is not new in the real-valued case (it can be obtained with Malliavin's calculus), but the method can be extended to the manifold-valued case (this is sketched at the end of the section). We do not try to prove precise estimates with the $L^{q}$ norm of $f\left(X_{t}\right)$ as in previous sections, but only with the supremum $\|f\|_{\infty}$ of $|f|$.

Theorem 4. Suppose that $M$ is compact and that $T_{x} M$ is for any $x \in M$ generated by the vector fields $\Xi_{i}$ and $\Xi_{i j}=\left[\Xi_{i}, \Xi_{j}\right]$ taken at point $x$. Then there exists a $C>0$ such that

$$
\left|d\left(P_{t} f\right)(x)\right| \leq \frac{C}{t \wedge 1}\|f\|_{\infty}
$$

for any $t>0$ and any bounded Borel function $f$.
Proof. We are going to prove the result for $f$ smooth and $t \leq 1$. We will denote the vector fields $\Xi_{i}$ and $\Xi_{i j}$ taken at $x$ by $\xi_{i}(x)$ and $\xi_{i j}(x) \in T_{x} M$ (we keep the upper case letters to denote the vector fields considered as acting on functions). We consider the relation

$$
d\left(P_{t} f\right)(x)=\frac{2}{t} \mathbb{E} \int_{0}^{t / 2} d\left(P_{t-s} f\right)\left(X_{s}\right) J_{s} d s
$$

Our hypoellipticity condition implies that we can write the Jacobian $J_{s}$ taken on some vector $\vec{e} \in T_{x} M$ as

$$
\begin{equation*}
J_{s} \vec{e}=\sum_{i} \psi_{s}^{i} \xi_{i}\left(X_{s}\right)+\sum_{i j} \psi_{s}^{i j} \xi_{i j}\left(X_{s}\right) . \tag{4.1}
\end{equation*}
$$

with $\left|\psi_{s}^{i}\right|,\left|\psi_{s}^{i j}\right| \leq C\left|J_{s}\right|$; in particular the moments of $\psi_{s}^{i}$ and $\psi_{s}^{i j}$ are bounded. Thus

$$
\begin{align*}
d\left(P_{t} f\right)(x) \vec{e}= & \frac{2}{t} \sum_{i} \mathbb{E} \int_{0}^{t / 2} \Xi_{i}\left(P_{t-s} f\right)\left(X_{s}\right) \psi_{s}^{i} d s \\
& +\frac{2}{t} \sum_{i j} \mathbb{E} \int_{0}^{t / 2} \Xi_{i j}\left(P_{t-s} f\right)\left(X_{s}\right) \psi_{s}^{i j} d s \tag{4.2}
\end{align*}
$$

The first type of terms can be estimated by means of the quadratic variation of the martingale $Y_{s}$ like previously, and is of order $1 / \sqrt{t}$; thus it is sufficient to study the second type, and therefore to estimate $\Xi_{i j}\left(P_{t} f\right)$. To this end, embed $M$ into an Euclidean space, extend the vector fields $\Xi_{i}$ to $C^{\infty}$ vector fields with compact support, and write the equation for $X_{s}$ in It's form

$$
\begin{equation*}
X_{s}=x+\int_{0}^{s} b\left(X_{u}\right) d u+\sum_{k} \int_{0}^{s} \xi_{k}\left(X_{u}\right) d W_{u}^{k} \tag{4.3}
\end{equation*}
$$

Then

$$
\begin{equation*}
\xi_{i}\left(X_{s}\right)=\xi_{i}(x)+\sum_{k} \Xi_{k} \xi_{i}(x) W_{s}^{k}+O(s) \tag{4.4}
\end{equation*}
$$

in the spaces $L^{q}$ for $s$ small, and

$$
\begin{align*}
\xi_{i}\left(X_{s}\right) W_{s}^{j}= & \int_{0}^{s} \xi_{i}\left(X_{u}\right) d W_{u}^{j}+\int_{0}^{s} W_{u}^{j} d \xi_{i}\left(X_{u}\right)+\left\langle\xi_{i}(X), W^{j}\right\rangle_{s} \\
= & \xi_{i}(x) W_{s}^{j}+\sum_{k} \Xi_{k} \xi_{i}(x)\left(\int_{0}^{s} W_{u}^{k} d W_{u}^{j}\right. \\
& \left.+\int_{0}^{s} W_{u}^{j} d W_{u}^{k}\right)+\Xi_{j} \xi_{i}(x) s+O\left(s^{3 / 2}\right) . \tag{4.5}
\end{align*}
$$

Now, for $(i, j)$ fixed, let us apply an infinitesimal rotation on the Wiener process ( $W_{s}^{j}, W_{s}^{i}$ ), and an infinitesimal modification on the initial condition in the direction $t \xi_{i j}(x)$ ( $t$ is now a small positive parameter; it will be later interpreted as a time parameter); this means that $\left(W_{s}^{j}, W_{s}^{i}\right)$ is replaced by

$$
\left(W_{s}^{j} \cos \varepsilon+W_{s}^{i} \sin \varepsilon,-W_{s}^{j} \sin \varepsilon+W_{s}^{i} \cos \varepsilon\right)
$$

and that $x$ is replaced by $x+\varepsilon t \xi_{i j}(x)$; we denote the perturbed process by $X_{s}^{\varepsilon}$. Then the differentiation of (4.3) shows that the derivative $V_{s}$ of $\varepsilon \mapsto X_{s}^{\varepsilon}$ at $\varepsilon=0$ is solution of

$$
\begin{align*}
V_{s}= & t \xi_{i j}(x)+\int_{0}^{s}(d b)\left(X_{u}\right) V_{u} d u+\sum_{k} \int_{0}^{s}\left(d \xi_{k}\right)\left(X_{u}\right) V_{u} d W_{u}^{k} \\
& +\int_{0}^{s} \xi_{j}\left(X_{u}\right) d W_{u}^{i}-\int_{0}^{s} \xi_{i}\left(X_{u}\right) d W_{u}^{j} . \tag{4.6}
\end{align*}
$$

This process is of order $t+\sqrt{s}$ for $s$ and $t$ small, and

$$
V_{s}=t \xi_{i j}(x)+\xi_{j}(x) W_{s}^{i}-\xi_{i}(x) W_{s}^{j}+O(t \sqrt{s}+s)
$$

By applying this estimate to the terms $V_{u}$ of (4.6), and by using also (4.4), we obtain the more precise expansion

$$
\begin{aligned}
V_{s}= & t \xi_{i j}(x)+\xi_{j}(x) W_{s}^{i}-\xi_{i}(x) W_{s}^{j} \\
& +\Xi_{j} \xi_{k}(x) \int_{0}^{s} W_{u}^{i} d W_{u}^{k}-\Xi_{i} \xi_{k}(x) \int_{0}^{s} W_{u}^{j} d W_{u}^{k} \\
& +\Xi_{k} \xi_{j}(x) \int_{0}^{s} W_{u}^{k} d W_{u}^{i}-\Xi_{k} \xi_{i}(x) \int_{0}^{s} W_{u}^{k} d W_{u}^{j}+O\left(t \sqrt{s}+s^{3 / 2}\right)
\end{aligned}
$$

where the expressions involving $k$ have to be summed. In this equation, the vector fields are taken at $x$; we use (4.5) in order to give an approximate expression of $V_{s}$ as a linear combination of vector fields taken at $X_{s}$. By using $\Xi_{k} \xi_{j}-\Xi_{j} \xi_{k}=\xi_{k j}$, we check after a calculation that

$$
\begin{aligned}
V_{s}= & (t-s) \xi_{i j}\left(X_{s}\right)+\xi_{j}\left(X_{s}\right) W_{s}^{i}-\xi_{i}\left(X_{s}\right) W_{s}^{j} \\
& +\xi_{k i}\left(X_{s}\right) \int_{0}^{s} W_{u}^{j} d W_{u}^{k}-\xi_{k j}\left(X_{s}\right) \int_{0}^{s} W_{u}^{i} d W_{u}^{k}+O\left(t \sqrt{s}+s^{3 / 2}\right)
\end{aligned}
$$

The law of $X_{s}$ is sensible to the perturbation of the initial condition, but not to the rotation of the Wiener process; this means that $X_{s}^{\varepsilon}$ is still a diffusion with the same semigroup, so $\left(P_{s-u} f\right)\left(X_{u}^{\varepsilon}\right)$ is a martingale for any $\varepsilon$; after differentiation, we deduce that $d\left(P_{s-u} f\right)\left(X_{u}\right) V_{u}, 0 \leq u \leq s$ is a martingale with initial value $\Xi_{i j}\left(P_{s} f\right)(x) t$. Thus

$$
\begin{align*}
\Xi_{i j}\left(P_{s} f\right)(x)= & \mathbb{E}\left[d f\left(X_{s}\right) V_{s}\right] / t \\
= & \mathbb{E}\left[(1-s / t) \Xi_{i j} f\left(X_{s}\right)+\Xi_{j} f\left(X_{s}\right) W_{s}^{i} / t\right. \\
& -\Xi_{i} f\left(X_{s}\right) W_{s}^{j} / t+\Xi_{k i} f\left(X_{s}\right) \int_{0}^{s} W_{u}^{j} d W_{u}^{k} / t  \tag{4.7}\\
& \left.-\Xi_{k j} f\left(X_{s}\right) \int_{0}^{s} W_{u}^{i} d W_{u}^{k} / t\right]+\mathbb{E}\left[O\left(\sqrt{s}+s^{3 / 2} / t\right)\left|d f\left(X_{s}\right)\right|\right] .
\end{align*}
$$

We let now $t$ be the time parameter, and we write

$$
\Xi_{i j}\left(P_{t} f\right)=\frac{n}{t} \int_{0}^{t / n} \Xi_{i j}\left(P_{s} P_{t-s} f\right) d s
$$

for some integer $n \geq 2$ which will be chosen later; we express the right hand side by applying (4.7) with $P_{t-s} f$ instead of $f$. Some of the terms can be estimated; the term

$$
\begin{aligned}
& \frac{n}{t^{2}} \int_{0}^{t / n} \Xi_{j}\left(P_{t-s} f\right)\left(X_{s}\right) W_{s}^{i} d s \\
& \quad \leq \frac{n}{t^{2}}\left(\int_{0}^{t / n}\left|\Xi_{j}\left(P_{t-s} f\right)\left(X_{s}\right)\right|^{2} d s\right)^{1 / 2}\left(\int_{0}^{t / n}\left(W_{s}^{i}\right)^{2} d s\right)^{1 / 2}
\end{aligned}
$$

can be estimated as in Theorem 1 by means of the quadratic variation of the martingale $P_{t-s} f\left(X_{s}\right)$ and is $O(1 / t)\|f\|_{\infty}$. From our hypoellipticity assumption, the derivative $d\left(P_{t-s} f\right)$ can be expressed as a combination of $\Xi_{k}\left(P_{t-s} f\right)$ and of $\Xi_{k l}\left(P_{t-s} f\right)$, and

$$
\frac{n}{t} \int_{0}^{t / n}\left|\Xi_{k}\left(P_{t-s} f\right)\left(X_{s}\right)\right| O\left(\sqrt{s}+s^{3 / 2} / t\right) d s=O(1)\|f\|_{\infty}
$$

by using again the quadratic variation. We obtain

$$
\begin{aligned}
\Xi_{i j}\left(P_{t} f\right)(x)= & \mathbb{E}\left[\frac{n}{t} \int_{0}^{t / n}\left(1-\frac{s}{t}\right) \Xi_{i j}\left(P_{t-s} f\right)\left(X_{s}\right) d s\right. \\
& \left.+\frac{n}{t} \int_{0}^{t / n} \Xi_{K}\left(P_{t-s} f\right)\left(X_{s}\right)\left(\frac{G_{i j}^{K}\left(R_{s}\right)}{t}+O(\sqrt{s})\right) d s\right] \\
& +O(1 / t)\|f\|_{\infty},
\end{aligned}
$$

where the expression is summed over indices $K=\left(k_{1}, k_{2}\right)$, where $R_{s}$ consists of the double integrals of the process $W_{s}$, and where $G_{i j}^{K}$ are linear forms. Thus the vector $\Xi\left(P_{t} f\right)=\left(\Xi_{K}\left(P_{t} f\right)\right)$ is solution of

$$
\Xi\left(P_{t} f\right)(x)=\frac{n}{t} \mathbb{E} \int_{0}^{t / n}\left(I-A_{s}\right) \Xi\left(P_{t-s} f\right)\left(X_{s}\right) d s+O(1 / t)\|f\|_{\infty}
$$

for a matrix-valued process $A_{s}$ satisfying

$$
A_{s}=\frac{s}{t} I-\frac{G\left(R_{s}\right)}{t}+O(\sqrt{s})
$$

for a linear map $G$. The procedure can be iterated in order to express $\Xi\left(P_{t-s} f\right)\left(X_{s}\right)$, and we obtain

$$
\begin{aligned}
\Xi\left(P_{t} f\right)(x)= & \frac{n^{2}}{t^{2}} \mathbb{E} \int_{0}^{t / n} \int_{t / n}^{2 t / n}\left(I-A_{s_{1}}\right)\left(I-A_{s_{1} s_{2}}\right) \Xi\left(P_{t-s_{2}} f\right)\left(X_{s_{2}}\right) d s_{2} d s_{1} \\
& +O(1 / t)\|f\|_{\infty}
\end{aligned}
$$

with

$$
A_{s_{1} s_{2}}=\frac{s_{2}-s_{1}}{t} I-\frac{G\left(R_{s_{1} s_{2}}\right)}{t}+O\left(\sqrt{s_{2}-s_{1}}\right)
$$

and where $R_{s_{1} s_{2}}$ consists of the double integrals of the increments of $W$ on $\left[s_{1}, s_{2}\right]$. After $n$ iterations, we get

$$
\begin{array}{r}
\Xi\left(P_{t} f\right)(x)=\frac{n^{n}}{t^{n}} \mathbb{E} \int_{0}^{t / n} \cdots \int_{(n-1) t / n}^{t}\left(I-A_{s_{1}}\right) \ldots\left(I-A_{s_{n-1} s_{n}}\right)  \tag{4.8}\\
\Xi\left(P_{t-s_{n}} f\right)\left(X_{s_{n}}\right) d s_{n} \ldots d s_{1}+O(1 / t)\|f\|_{\infty} .
\end{array}
$$

Consider now the process

$$
\bar{A}_{s_{1} s_{2}}=\frac{s_{2}-s_{1}}{t} I-\frac{G\left(R_{s_{1} s_{2}}\right)}{t}
$$

The variable $G\left(R_{s_{i-1} s_{i}}\right)$ is of order $s_{i}-s_{i-1}$, and its conditional expectation given the process $W$ up to time $s_{i-1}$ is 0 . By applying classical techniques (such as those which are used for the time discretization of stochastic differential equations), we can deduce that

$$
\left(I-\bar{A}_{s_{1}}\right) \ldots\left(I-\bar{A}_{s_{n-1} s_{n}}\right)
$$

converges in the spaces $L^{q}$ to $e^{-1} I$ as $n \rightarrow \infty$, uniformly for $\left(s_{1}, \ldots, s_{n}\right)$ in the integration domain of (4.8). Thus the $L^{1}$ norm of the operator norm of this variable is close to $e^{-1}$ if $n$ is chosen large enough; let us fix such an $n$. Then, if $t$ is small enough, we deduce that

$$
\begin{equation*}
\left\|\mid\left(I-A_{s_{1}}\right) \ldots\left(I-A_{s_{n-1} s_{n}}\right)\right\|_{1} \leq 1 / 2 \tag{4.9}
\end{equation*}
$$

and therefore

$$
\left|\Xi\left(P_{t} f\right)(x)\right| \leq \frac{1}{2} \sup _{s \leq t}\left\|\Xi\left(P_{s} f\right)\right\|_{\infty}+\frac{C}{t}\|f\|_{\infty}
$$

By using $P_{u}=P_{t} P_{u-t}$, this equation implies

$$
\left\|\Xi\left(P_{u} f\right)\right\|_{\infty} \leq \frac{1}{2} \sup _{u-t \leq s \leq u}\left\|\Xi\left(P_{s} f\right)\right\|_{\infty}+\frac{C}{t}\|f\|_{\infty}
$$

for $u \geq t$. Thus, if

$$
F(t)=\sup _{t \leq u \leq 1}\left\|\Xi\left(P_{u} f\right)\right\|_{\infty}
$$

then

$$
F(4 t) \leq \frac{1}{2} F(3 t)+\frac{C}{t}\|f\|_{\infty}
$$

for $t \leq 1 / 4$, and therefore

$$
\sup _{0 \leq t \leq 1 / 4}(4 t F(4 t)) \leq \frac{2}{3} \sup _{0 \leq t \leq 1 / 3}(3 t F(3 t))+4 C\|f\|_{\infty}
$$

Thus $t F(t)$ is dominated by $\|f\|_{\infty}$, and we conclude the proof from (4.2).

Remark 4.1. Consider (4.2) with $\vec{e}=\xi_{k}(x)$; then the left hand side is $\Xi_{k}\left(P_{t} f\right)(x)$; moreover, an analysis of (4.1) shows that $\psi_{s}^{i j}$ is in this case of order $\sqrt{s}$ (notice that $\psi_{0}^{i j}=0$ ). We can deduce that

$$
\left|\Xi_{k}\left(P_{t} f\right)(x)\right| \leq \frac{C}{\sqrt{t} \wedge 1}\|f\|_{\infty} .
$$

Thus, as $t \downarrow 0$, the Lipschitz coefficient of $P_{t} f$ is of order $1 / \sqrt{t}$ for the intrinsic subriemannian distance of the diffusion on $M$, and it is of order $1 / t$ for Riemannian distances.

Remark 4.2. If now we consider the general hypoelliptic case, then we have higher order brackets of $\left(\Xi_{i}\right)$ in (4.2). As it has been said in the proof, the vector fields $\Xi_{i}$ can be estimated on $P_{t} f$ by means of a quadratic variation; roughly speaking, they can be interpreted as Cameron-Martin perturbations on the driving Brownian motion $W_{t}$. Then the vector fields $\Xi_{i j}$ were estimated on $P_{t} f$ by means of rotations on $W_{t}$. However, we have no other absolutely continuous perturbation to estimate higher order brackets, so we think that the method cannot be extended to more general hypoelliptic situations.

The localization (see the framework of Theorem 2) does not cause much problem; we stop the processes at $\tau(r)$, and $\Xi h(t, x)$ is now expressed by means of variables $A_{s_{i-1} \wedge \tau(r), s_{i} \wedge \tau(r)}$; then we consider separately (like previously) the events $\{\tau(r)=r\}$ (on which we use the above estimations) and $\{\tau(r)<r\}$ (which has small probability). We obtain

$$
\left|Y_{0}^{\prime}\right| \leq \frac{C}{r}\|h\|_{\infty}+\frac{1}{4}\left\|Y_{\tau(r)}^{\prime}\right\|_{q}
$$

with $Y_{s}^{\prime}=\Xi h\left(Z_{s}\right)$. We multiply by $\rho_{\star}^{2}\left(Z_{0}\right)$ instead of $\rho_{\star}\left(Z_{0}\right)$, and proceed as in Theorem 2. The result is

$$
|d h(t, x)| \leq \frac{C_{K}}{t \wedge \rho^{2}(x) \wedge 1}\|h\|_{\infty} .
$$

The extension to the manifold-valued case (framework of Theorem 3) can also be worked out; the main difference is that the equality (4.7) should be replaced by an inequality with an $L^{p}$ norm; then the estimation (4.9) for the $L^{1}$ norm can also be done with the $L^{p}$ norm, and we can prove

$$
|d h(t, x)| \leq \frac{C_{K}}{t \wedge \rho^{2}(x) \wedge 1} \sup _{\left(z, z^{\prime}\right)} \delta\left(h(z), h\left(z^{\prime}\right)\right) .
$$

Acknowledgement. The author wishes to thank the referees for valuable comments on a first version of this work.

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